

# Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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**Potential competing interests:** No potential competing interests to declare.

The innovation of this paper is to propose the design, development, and application of an intelligent adaptive hybrid controller to control and stabilise the drone. But according to the relative introduction, this innovation is not prominent and some explanations are not clear. The comparative comparison experiment is necessary to highlight the advantages of the proposed method. More detailed explanations are also necessary.