

Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

Mohamed Metwally¹

¹ Aswan University

Potential competing interests: No potential competing interests to declare.

1. ***Abstract should be concise about work presented in the paper.***
2. ***Literature review is not up to the mark.***
3. ***I strongly suggest a change in the writing style of the introductory section, splitting it into several subsections to make it more readable.***
4. ***Author should provide the comparative analysis between proposed work with existing method.***
5. ***Proposed technique should be explained with novelty.***
6. ***Contribution of author should be providing in the manuscript.***
7. ***Results section should be explained comprehensively with positive points of the proposed work.***
8. ***Equation parameters are not described properly.***
9. ***Figures quality are very poor and cited from other sources. If not new why you add. Add the novelty only.***
10. ***The paper quality is poor and have many typos. Kindly revise the paper.***
11. ***Conclusion section should include the numerical results of the proposed work***
12. The following works may help you:
 - <https://doi.org/10.1080/02286203.2022.2139128>
 - <https://doi.org/10.1371/journal.pone.0293613>
 - [10.1109/ACCESS.2023.3234996](https://doi.org/10.1109/ACCESS.2023.3234996)
 - <https://doi.org/10.1371/journal.pone.0293246>