Review of: "System and Method for One or More Extruders Using a Robotic Arms to Print a 3D Model"

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Potential competing interests: No potential competing interests to declare.

The primary goal of the manuscript—using robotic arms to facilitate 3D printing with many extruders—is communicated well. The goal is apparent, and the introduction gives the readers a solid backdrop to put everything in perspective.

The technique section is clearly laid out and provides a detailed explanation of the use of robotic arms, but certain precise technical information is missing, such as the kind of robotic arm that was utilized, the materials that were examined, and the printing parameters. The study's repeatability would be improved by including these specifics.

The results are presented in an understandable manner, and the inclusion of figures facilitates comprehension. A detailed explanation of how this strategy differs from or enhances existing techniques will greatly enhance the research. Thus, a more thorough examination is possible.

You may cite these references-

Rozaini, I. A., Ahmad Zakey, N. E. N., Mohd Zaman, M. H., Ibrahim, M. F., Mustaza, S. M., & Mohamed Moubark, A. (2023). Bilateral Teleoperation with a Shared Design of Master and Slave Devices for Robotic Excavators in Agricultural Applications. International Journal of Experimental Research and Review, 35, 119-127. https://doi.org/10.52756/ijerr.2023.v35spl.011

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