

# Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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**Potential competing interests:** No potential competing interests to declare.

1. What are the necessities of lift coefficient, drag coefficient, pitch coefficient, and thrust coefficient in your proposed system?
2. Explain Fuzzy interference system in brief.
3. More details required how ANFIS-PID shows improved performance and stability of Drone Flight as compared to traditional PID.
4. Cite the most recent work in related work
5. For example cite this work Ghosh, R., Mohanty, S., & Pattnaik, P. K. (2021). An evolving  $\alpha$ -dependent mobility model for a fleet of unmanned aerial vehicles in wireless sensor networks. *International Journal of Communication Systems*, 34(14), e4926
6. What will the future work of your proposed work.
7. Fig. 2 is not clear.
8. Check grammatical and typo errors.
9. Arrange the paper in more organized way.