

Review of: "Optimal Latency Compensator for Improved Performance of Teleoperated UGVs on Soft Terrains"

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Potential competing interests: No potential competing interests to declare.

In this work, the authors investigated the performance of delayed-based bilateral teleoperation on soft terrains. The topic is interesting, and the results seem correct. After carefully reading this paper, my comments are:

1. The clarity of writing should be improved to explain the key insights and significance of the analytical results. In the introduction, the author should highlight the significant technical challenge of the analysis compared to previous works and summarize new insights provided by the results of this work
2. The introduction could be better quality, and the papers must be appropriately cited.
3. The write-up could be better organized.
4. Typo mistakes should be improved.