

Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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Potential competing interests: No potential competing interests to declare.

The paper presents a hybrid approach for UAV quadcopter control. The purpose and methodology are described clearly, although in some cases redundant (the dynamics part could be summarized better). The overall content is interesting, but lacks any real new features. In particular, it should be better underlined how the desired robustness is achieved in highly critical contexts with more in-depth simulations.