Research Article

# [Withdrawn] AirIO: Learning Inertial Odometry with Enhanced IMU Feature Observability — air-io.github.io

Yuheng Qiu[1], Can Xu[1], Yutian Chen[1], Shibo Zhao[1], Junyi Geng[2], Sebastian Scherer[1]

1. Robotics Institute, Carnegie Mellon University, United States; 2. Department of Aerospace Engineering, Pennsylvania State University, United States

**This manuscript has been withdrawn.**

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## Declarations