Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

Javier Viana[1]

1 Massachusetts Institute of Technology

Potential competing interests: No potential competing interests to declare.

- The equations 1-10 are labeled, but the next equations are not.
- The reader is confused with all these many equations not being embedded as part of the text to describe the problem better.
- The variables of the equations should be described better, i.e., the Euler Angles. Non-educated readers get lost easily.
- There are several typos in the text, text should be revised.
- The english of the text should be improved.
- Reference [Etkin, 1972] should embedded in text.
- Figure 3 adds no information.
- Figures 5 to 9 are not described enough, the reader is lost very easily.
- I am afraid this is a low quality research article, the authors claim to comprehend adaptive control, intelligent control, hybrid control, and aeronautical characteristics of a UAV-drone flight, but the it looks more like the problem set of an undergraduate course than a fleshed out research article.
- The research is interesting and if the project is improved technically it could lead to a very relevant paper.