Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

Dr,Binu Ben Jose[1]

1 Vellore Institute of Technology

1. The paper must undergo grammatical checks.

2. What do the author infer from the equations 1 to 15? What is the numerical result of the equations pertaining to the drone?

3. Figures 1 and 2 are the fundamental ones. This reviewer is unable to find a research component here.

4. The MATLAB figures need to be modified to have white background. The quality must also be improved.

5. The proposed work with incomplete information and incomplete simulation results is found to be infeasible.

6. For control systems, stability is an important concept which is lagging in this paper.

7. Simple work must be supported by experimental hardware results.

8. Hence, the paper may not be suitable for publication in the current form.