Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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Potential competing interests: No potential competing interests to declare.

1. The numerical simulation results are promising and demonstrate the effectiveness of the proposed method.

2.The authors provide a clear explanation of the methodology and the numerical experiments, which makes it easy to understand and replicate the results.

3. The article is well-written and structured, with a clear introduction, methodology, results, and discussion.

4. One potential limitation of the study is that the numerical experiments are conducted under white-noise disturbance, which may not reflect the real-world conditions of quadcopter drones.

5. Future research could explore the effectiveness of the proposed method under more realistic scenarios and compare it with other control techniques.

6. Overall, the article is a valuable contribution to the field of autonomous drone flight and adaptive control.