

# Review of: "Optimal Latency Compensator for Improved Performance of Teleoperated UGVs on Soft Terrains"

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**Potential competing interests:** No potential competing interests to declare.

- The article is well-structured, with a clear introduction, objective, methodology, and results.
- The proposed genetic algorithm-based predictor framework appears to be a promising solution, backed by experimental validation.
- The identification of a critical latency threshold adds practical significance to the study.
- The article effectively communicates the potential impact of the research on improving UGV teleoperation in lunar exploration.