

Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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Potential competing interests: No potential competing interests to declare.

1. The test bench before and after simplification with its corresponding mathematical model.
2. The proposed theoretical method of the LQR controller and data generation for ANFIS is non-existent such as: the effect of coupling between the outputs of your system, the use of observers for a complete state vector, the measurement of functions autocorrelation and intercorrelation of the data generatedetc.
3. The figures of FIS training error, the produced surface of the final trained FIS, as well as its evaluation based on experimental data are missing.