Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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Potential competing interests: No potential competing interests to declare.

UAVS control is an intensely studied topic, so it should be addressed with more substantial contributions, such as complete dynamics, disturbances, and complex trajectories.

The method needs to be completely clear. Further explanation is necessary to understand the contribution.

Improving images is required; The black background should be removed to appreciate the information.

Placing the graphs separately and redisplay the same information on another graph is unnecessary. (Fig. 12-14)