

Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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Potential competing interests: No potential competing interests to declare.

The current proposes to study and comprehend adaptive control, intelligent control, hybrid control, and aeronautical characteristics of a UAV-drone flight. The theory is validated using simulations.

Comments to authors:

- Please add more details of how the theory from the first sections is applied in the results section.
- The authors can add the steps of implementing the algorithms. The theoretical part can be better detailed. The steps will be to the benefit of the readers, maybe they'll help the readers to implement the proposed algorithm.
- Add both the advantages and the disadvantages of the proposed method, in the current version of the paper only the advantages are presented.
- The state of the art it is poor maybe the author could add other publications related to the discussed topic.
- Add the measurement unit labels for abscissa and ordinate for all the figures from the paper.
- The quality of the figures can be improved since in the current version the figures are print screens from Simulink.
- Please add more comments regarding the obtained results, and what initial conditions were used to obtain the current results?