

# Review of: "Can artificial jellyfish be the next pragmatic autonomous self-deployable actuator?"

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**Potential competing interests:** No potential competing interests to declare.

The submitted article reviews a promising development in the field of soft robotics with the use of different actuators in a biomimetic jellyfish robot. While it highlights several advantages, a more comprehensive exploration of potential applications would strengthen the argument for artificial jellyfish as pragmatic autonomous self-deployable actuators. Additionally, please consider addressing challenges related to the behavior of each actuator type in dynamic environments with real-world scenarios and elaborate on the significance of silent operation and discreet actuation in the context of soft robotics applications.