

# Review of: "Optimal Latency Compensator for Improved Performance of Teleoperated UGVs on Soft Terrains"

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**Potential competing interests:** No potential competing interests to declare.

This paper is well organized with good logic. It can be noted that the performance can be improved with the proposed compensator. The figs and content are also acceptable with the good qualities. Some comment can be found below for further improvement,

1. The contribution can be further highlighted by comparing the existing work with this work.
2. The research gap can be further described to highlight the research motivation.
3. The authors's work are under a specific scenario, some general conclusion should be given because the results based on the certain model cannot directly offer guidance for practical application.
4. The case study is good and convincing.