Review of: "Optimal Latency Compensator for Improved Performance of Teleoperated UGVs on Soft Terrains"

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Potential competing interests: No potential competing interests to declare.

The work is interesting, well-written, and structured; however, some points could be improved:

1. It is not clear how the system would be deployed in real time. Would the GA be used in a real-time deployment, or is it only thought for simulations?

2. How would the delays be estimated in a real-time deployment?

3. How would the system work in a real deployment with varying delays?

4. What is the configuration of the GA? Population size, mutation and crossing rates, etc.