

# Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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**Potential competing interests:** No potential competing interests to declare.

The theme covered in this article is current and the manuscript is generally well written, but I do have a few remarks concerning the development of the control technique used.

I start first with the title which mentions the use of a command based on adaptive control, but the article does not specify in any way the use of this approach.

In addition, the authors specify that the main problem for UAVs systems is their stability, but they did not prove that the proposed control can stabilise a drone flight (section 4).

The mathematical equations given in the article are insufficient and do not explain the used approach.

I would have liked to see a comparison of the simulation results with other articles to see the improvements obtained.