

Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

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Potential competing interests: No potential competing interests to declare.

This paper proposes the design, development, and application of an intelligent adaptive hybrid controller to control and stabilise the drone. The writing of the whole paper is OK. However, some comments need to be revised.

1. Figs.3-10 12-14 should be clearly shown.
2. The references are very old the references should be updated.
3. In "Experiments" section, how the tool "Neuro-Fuzzy" operates on the example?
4. In equation (16), $A=?$, $B=?$