

Review of: "Neuro-Fuzzy-Based Adaptive Control for Autonomous Drone Flight"

Hao Xu¹

¹ Nanjing University of Information Science and Technology

Potential competing interests: No potential competing interests to declare.

This paper studies a novel design, development, and application of an intelligent adaptive hybrid controller to control and stabilise the drone.

- 1.The formulas in the article are best centered.
- 2.It's better to add a comparative experiment with existing methods.
- 3.The simulated image background can be changed to white.
- 4.Some spelling errors and typos should be corrected.