

# Review of: "System and Method for One or More Extruders Using a Robotic Arms to Print a 3D Model"

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**Potential competing interests:** No potential competing interests to declare.

## **Abstract:**

The abstract outlines a novel approach for 3D printing using two robotic arms, emphasizing improved printing time and accuracy. The innovative concept is highlighted, focusing on a system that adjusts the bed's angle to avoid entanglement of the arms and implements local software development.

## **Introduction:**

The introduction sets a clear context for the study, referencing historical advancements in 3D printing and explaining the limitations of existing methods. It successfully lays the groundwork for the proposed system, creating a compelling argument for its necessity.

## **Illustrations:**

The illustrations, including system diagrams and flow charts, effectively depict the proposed 3D printing system. These visual aids are crucial for understanding the complex mechanical and software interactions within the system.

## **Conclusion:**

The conclusion reinforces the potential benefits of the system, such as its capability to print various shapes and sizes with different materials. It emphasizes the system's flexibility and the use of local materials in its construction.

## **Conflict of Interest:**

No conflict of interest is declared, and the acknowledgement section credits the Cambridge Institute of Technology and various individuals for their contributions, which adds credibility to the study.

## **Assessment:**

The topic is highly relevant, addressing a key area of innovation in additive manufacturing. The approach of using robotic arms for 3D printing promises to enhance efficiency and versatility.

The system's novelty lies in its unique configuration of robotic arms and the software developed for precise control, marking a significant advancement in the field.

The article could benefit from a more detailed analysis of the system's performance, such as specific improvements in speed and accuracy compared to traditional 3D printers.

Inclusion of comparative data, either through simulations or practical trials, would further substantiate the claims of enhanced efficiency and accuracy.

The paper is well-structured and written in a clear, concise manner. However, expanding the technical details, particularly in the methodology section, would provide a deeper understanding of the system's operations.

Future research directions or potential applications, especially in industrial settings, would enhance the article's practical implications.

In conclusion, the paper presents a significant innovation in 3D printing technology. Its strengths lie in its novel approach and clear presentation. Further empirical data and technical details would strengthen its contribution to the field of additive manufacturing.